

MATEMATIČKE METODE FIZIKE I

Drugi kolokvij 2. 2. 2024.

ZADATAK 1 Nađite divergenciju i rotaciju vektorskog polja

$$\mathbf{v} = \rho(2 + \sin^2 \phi) \mathbf{e}_\rho + \rho \sin \phi \cos \phi \mathbf{e}_\phi + 3z \mathbf{e}_z$$

ZADATAK 2 Pokažite da vektori Frenetovog trobrida krivulje

$$\mathbf{r}(t) = e^t \cos t \mathbf{e}_x + e^t \sin t \mathbf{e}_y + e^t \mathbf{e}_z$$

zatvaraju konstantne kutove sa z-osi.

ZADATAK 3 Izračunajte krivuljni integral

$$\oint_C [(e^x y + \cos x \sin y) dx + (e^x + \sin x \cos y) dy]$$

po elipsi $x^2/a^2 + y^2/b^2 = 1$.

ZADATAK 4 (a) Pokažite da plošni integral

$$\int_\sigma (4xyz dx dy - 2x^2 y dy dz - 3xz^2 dx dz)$$

ne ovisi o površini $S(\sigma)$ nego samo o njenoj rubnoj krivulji C .

(b) Transformirajte plošni integral pod (a) u krivuljni integral po rubnoj krivulji C te ga izračunajte ako je rubna krivulja zadana jednadžbama:

$$x^2 + y^2 = R^2, \quad x + z = 0$$

Uputa: napišite zadani integral u obliku

$$\int_\sigma \mathbf{A} \cdot \mathbf{n} dS$$

te provjerite je li \mathbf{A} solenoidalno polje.

ZADATAK 5 Izračunajte plošni integral vektorskog polja \mathbf{A}

$$\mathbf{A}(\mathbf{r}) = (x^2 + y^2 + z^2)(x\mathbf{e}_x + y\mathbf{e}_y + z\mathbf{e}_z)$$

po sferi $R^2 = x^2 + y^2 + z^2$. Računajte direktno i nakon toga računajte pomoću teorema o divergenciji.

8.3

Divergencija u cilindričkim koordinatama:

$$\vec{v} = v_\rho \vec{e}_\rho + v_\varphi \vec{e}_\varphi + v_z \vec{e}_z$$

$$\operatorname{div} \vec{v} = \vec{\nabla} \cdot \vec{v} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho v_\rho) + \frac{1}{\rho} \frac{\partial v_\varphi}{\partial \varphi} + \frac{\partial v_z}{\partial z}$$

$$\vec{v} = \underbrace{\rho(2 + \sin^2 \varphi)}_{v_\rho} \vec{e}_\rho + \underbrace{\rho \sin \varphi \cos \varphi}_{v_\varphi} \vec{e}_\varphi + \underbrace{3z}_{v_z} \vec{e}_z$$

$$\begin{aligned} \vec{\nabla} \cdot \vec{v} &= \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho^2 (2 + \sin^2 \varphi)) + \frac{1}{\rho} \frac{\partial}{\partial \varphi} (\rho \sin \varphi \cos \varphi) + \frac{\partial}{\partial z} (3z) \\ &= \frac{1}{\rho} (2\rho(2 + \sin^2 \varphi)) + \frac{1}{\rho} \cdot \rho \cdot \frac{1}{2} \cos 2\varphi \cdot 2 + 3 \\ &= 2(2 + \sin^2 \varphi) + \cos 2\varphi + 3 \\ &= 4 + 2\sin^2 \varphi + \cos^2 \varphi - \sin^2 \varphi + 3 \\ &= \underline{\underline{8}} \end{aligned}$$

Rotacija u cilindričkim koordinatama:

$$\begin{aligned} \operatorname{rot} \vec{v} = \vec{\nabla} \times \vec{v} &= \left(\frac{1}{\rho} \frac{\partial v_z}{\partial \varphi} - \frac{\partial v_\varphi}{\partial z} \right) \vec{e}_\rho + \left(\frac{\partial v_\rho}{\partial z} - \frac{\partial v_z}{\partial \rho} \right) \vec{e}_\varphi \\ &+ \left(\frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho v_\varphi) - \frac{1}{\rho} \frac{\partial v_\rho}{\partial \varphi} \right) \vec{e}_z \end{aligned}$$

$$\begin{aligned} \operatorname{rot} \vec{v} &= \left[\frac{1}{\rho} \frac{\partial}{\partial \varphi} (3z) - \frac{\partial}{\partial z} (\rho \sin \varphi \cos \varphi) \right] \vec{e}_\rho + \left[\frac{\partial}{\partial z} (\rho(2 + \sin^2 \varphi)) - \frac{\partial}{\partial \rho} (3z) \right] \vec{e}_\varphi \\ &+ \left[\frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho^2 \sin \varphi \cos \varphi) - \frac{1}{\rho} \frac{\partial}{\partial \varphi} (\rho(2 + \sin^2 \varphi)) \right] \vec{e}_z \\ &= 0 \vec{e}_\rho + 0 \vec{e}_\varphi + \left[\underbrace{2 \sin \varphi \cos \varphi - 2 \sin \varphi \cos \varphi}_{=0} \right] \vec{e}_z \\ &= 0 \end{aligned}$$

Polje \vec{v} je konzervativno (bezvrtložno).

2.

Nadimo \vec{t} , \vec{b} i \vec{n} .

$$\vec{t} = \frac{\dot{\vec{r}}}{\|\dot{\vec{r}}\|}$$

$$\begin{aligned} \dot{\vec{r}} &= e^t (\cos t \vec{e}_x + \sin t \vec{e}_y + \vec{e}_z) + e^t (-\sin t \vec{e}_x \\ &\quad + \cos t \vec{e}_y) \\ &= e^t (\cos t - \sin t) \vec{e}_x + e^t (\sin t + \cos t) \vec{e}_y + e^t \vec{e}_z \end{aligned}$$

$$\|\dot{\vec{r}}\|^2 = (e^t)^2 \left[\underbrace{(\cos t - \sin t)^2}_{\cos^2 t + \sin^2 t - 2 \sin t \cos t} + \underbrace{(\sin t + \cos t)^2}_{\sin^2 t + \cos^2 t + 2 \sin t \cos t} + 1 \right]$$

$$= (e^t)^2 \cdot 3 \Rightarrow \|\dot{\vec{r}}\| = 3e^t$$

Imamo,

$$\vec{t} = \frac{1}{\sqrt{3}} \left[(\cos t - \sin t) \vec{e}_x + (\sin t + \cos t) \vec{e}_y + \vec{e}_z \right]$$

Mo,

$$\vec{t} \cdot \vec{e}_z = \frac{1}{\sqrt{3}}$$

pa smo za tangentu dokazali! Računamo binormalu

$$\vec{b} = \frac{\dot{\vec{r}} \times \ddot{\vec{r}}}{\|\dot{\vec{r}} \times \ddot{\vec{r}}\|}$$

$$\begin{aligned} \ddot{\vec{r}} &= \frac{d}{dt} \dot{\vec{r}} = \frac{d}{dt} \left\{ e^t \left[(\cos t - \sin t) \vec{e}_x + (\sin t + \cos t) \vec{e}_y + \vec{e}_z \right] \right\} \\ &= e^t \left[(\cos t - \sin t) \vec{e}_x + (\sin t + \cos t) \vec{e}_y + \vec{e}_z \right] \\ &\quad + e^t \cdot \left[(-\sin t - \cos t) \vec{e}_x + (\cos t - \sin t) \vec{e}_y \right] \end{aligned}$$

$$\ddot{\vec{r}} = e^{2t} \cdot (-2 \sin t) \vec{e}_x + 2 \cos t \vec{e}_y + \vec{e}_z$$

$$\begin{aligned} \dot{\vec{r}} \times \ddot{\vec{r}} &= \det \begin{pmatrix} \vec{e}_x & \vec{e}_y & \vec{e}_z \\ \cos t - \sin t & \sin t + \cos t & 1 \\ -2 \sin t & 2 \cos t & 1 \end{pmatrix} e^{2t} \\ &= \vec{e}_x \cdot \left[(\sin t + \cos t) - 2 \cos t \right] - \vec{e}_y \left[(\cos t - \sin t) + 2 \sin t \right] \\ &\quad + \vec{e}_z \left[2 \cos t (\cos t - \sin t) + 2 \sin t (\sin t + \cos t) \right] \\ &= \vec{e}_x \cdot (\sin t - \cos t) - \vec{e}_y (\cos t + \sin t) \\ &\quad + \vec{e}_z \cdot \underbrace{(2 \cos^2 t + 2 \sin^2 t)}_2 \end{aligned}$$

Jzus avog vektora jē

$$e^{2t} \left[(\sin t - \cos t)^2 + (\cos t + \sin t)^2 + 4 \right] = \sqrt{6} \cdot e^{2t}$$

Premā tase,

$$\begin{aligned} \vec{b} &= + \frac{\dot{\vec{r}} \times \ddot{\vec{r}}}{\|\dot{\vec{r}} \times \ddot{\vec{r}}\|} = + \frac{1}{\sqrt{6}} \left[\vec{e}_x (\sin t - \cos t) \right. \\ &\quad \left. - \vec{e}_y (\cos t + \sin t) + 2 \vec{e}_z \right] \end{aligned}$$

$$\vec{b} \cdot \vec{e}_z = \frac{2}{\sqrt{6}}$$

Na krājī, varamus $\vec{n} = \vec{b} \times \vec{t}$

$$\vec{n} = \frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{6}} \det \begin{pmatrix} \vec{e}_x & \vec{e}_y & \vec{e}_z \\ \sin t - \cos t & -\cos t - \sin t & 2 \\ \cos t - \sin t & \sin t + \cos t & 1 \end{pmatrix}$$

$$\vec{n} = \frac{1}{3\sqrt{2}} \left[\vec{e}_x \cdot (-\cos t - \sin t - 2 \sin t - 2 \cos t) \right. \\ \left. - \vec{e}_y (\sin t - \cos t - 2 \cos t + 2 \sin t) \right. \\ \left. + \vec{e}_z \left[\underbrace{(\sin t - \cos t)(\sin t + \cos t)}_{\sin^2 t - \cos^2 t} + \underbrace{(\sin t + \cos t)(\cos t - \sin t)}_{\cos^2 t - \sin^2 t} \right] \right]$$

$$\vec{n} = \frac{1}{3\sqrt{2}} \left[-3\vec{e}_x \cdot (\sin t + \cos t) - 3\vec{e}_y (\sin t - \cos t) \right] \\ = -\frac{1}{\sqrt{2}} \left[(\sin t + \cos t)\vec{e}_x + (\sin t - \cos t)\vec{e}_y \right]$$

pa 1e

$$\vec{n} \cdot \vec{e}_z = 0$$

10.5

Upotřebit číms Greenov theorem

$$\oint_C P dx + Q dy = \int_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

$$P = e^x y + \cos x \sin y$$

$$Q = e^x + \sin x \cos y$$

$$\frac{\partial Q}{\partial x} = e^x + \cos x \cos y$$

$$\frac{\partial P}{\partial y} = e^x + \cos x \cos y$$

Uvažmo,

$$\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = 0$$

pa je

$$\oint_C P dx + Q dy$$

po bito kojoj křivce C je rovno nula. Znači, radi se o konzervativním poli.

4.

(a) Navedeni integral moramo napisati u obliku

$$\int \vec{A} \cdot \vec{n} dS$$

$$\vec{n} = n_x \vec{e}_x + n_y \vec{e}_y + n_z \vec{e}_z \quad ; \quad n_x^2 + n_y^2 + n_z^2 = 1$$

Imamo

$$\int (-2x^2y dydz - 3xz^2 dx dz + 4xyz dx dy)$$

$$= \int (-2x^2y n_x - 3xz^2 n_y + 4xyz n_z) dS$$

Na primjer, $dx dy = n_z dS = \cos \varphi dS$
 gdje φ kut između normale i \vec{e}_z vektora

Vidimo da je

$$\vec{A} = -2x^2y \vec{e}_x - 3xz^2 \vec{e}_y + 4xyz \vec{e}_z$$

Je li \vec{A} solenoidalno?

$$\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$= -4xy + 0 + 4xy = 0$$

Jest! Prema tome, postoji vektorsko polje \vec{b} za kojeg
 vrijedi

$$\vec{A} = \vec{\nabla} \times \vec{b}$$

Sada treba pronaći to polje:

$$\vec{\nabla} \times \vec{b} = \det \begin{pmatrix} \vec{e}_x & \vec{e}_y & \vec{e}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ b_x & b_y & b_z \end{pmatrix} = \vec{e}_x \left(\frac{\partial b_z}{\partial y} - \frac{\partial b_y}{\partial z} \right) - \vec{e}_y \left(\frac{\partial b_z}{\partial x} - \frac{\partial b_x}{\partial z} \right) + \vec{e}_z \left(\frac{\partial b_y}{\partial x} - \frac{\partial b_x}{\partial y} \right)$$

Prva tačka,

$$1. \quad -2x^2y = \frac{\partial b_z}{\partial y} - \frac{\partial b_y}{\partial z}$$

$$2. \quad -3xz^2 = - \left(\frac{\partial b_z}{\partial x} - \frac{\partial b_x}{\partial z} \right)$$

$$3. \quad 4xyz = \frac{\partial b_y}{\partial x} - \frac{\partial b_x}{\partial y}$$

Uz jednačinu 1.

$$\frac{\partial b_z}{\partial y} = \frac{\partial b_y}{\partial z} - 2x^2y \quad / \int dy$$

$$b_z = -x^2y^2 + \int \frac{\partial b_y}{\partial z} dy$$

Uvrstimo u 2.

$$+3xz^2 = -2xy^2 + \int \frac{\partial^2 b_y}{\partial x \partial z} dy - \frac{\partial b_x}{\partial z}$$

Odavde je

$$\frac{\partial b_x}{\partial z} = -2xy^2 - 3xz^2 + \int \frac{\partial^2 b_y}{\partial x \partial z} dy \quad / \int dz$$

$$b_x = -2xy^2z - xz^3 + \int \frac{\partial b_y}{\partial x} dy$$

Uvrstimo u jednačinu 3.

$$4xyz = \frac{\partial b_y}{\partial x} - \left(-4xyz - 0 + \frac{\partial b_x}{\partial y} \right)$$

$$0 = 0$$

Vidimo da je b_y proizvoljna: odaberimo

$$b_y = 0$$

Imamo,

$$b_x = -2xy^2z - xz^3$$

$$b_y = 0$$

$$b_z = -x^2y^2$$

Sada integral po plohi možemo transformirati uo integral po krivici po Stokesovom teoremu

$$\int_S \vec{A} \cdot \vec{n} \, dS = \int_S (\vec{\nabla} \times \vec{b}) \cdot \vec{n} \, dS = \oint_C \vec{b} \cdot d\vec{e}$$

gdje C rubna krivica. Dakle, sveli smo plošni integral uo integral po rubnoj krivici C .

(5) Krivica

$$x^2 + y^2 = R^2$$

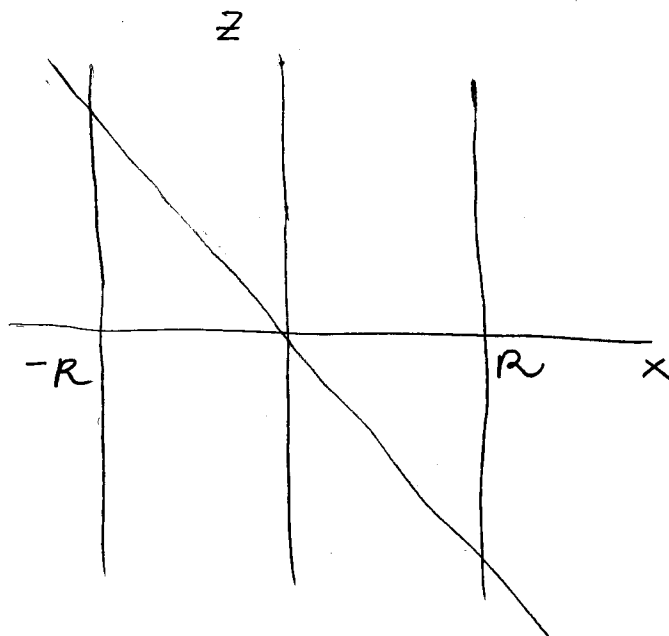
$$x + z = 0$$

Radi se o elipsi u prostoru. Možemo je parametrizirati

$$x = t$$

$$y^2 = R^2 - t^2$$

$$z = -t$$



Za pravdu u ovom slučaju

$$\vec{b} \cdot d\vec{e} = (-2xy^2z - xz^3) \cdot dx - x^2y^2dz$$

Uvratimo informaciju o krumelji u ovaj izraz

$$\begin{aligned} & [-2t(R^2 - t^2) \cdot (-t) - t \cdot (-t)^3] dt \\ & \quad - t^2 \cdot (R^2 - t^2) \cdot (-dt) \\ &= [2R^2t^2 - 2t^4 + t^4 + R^2t^2 - t^4] dt \\ &= [3R^2t^2 - 2t^4] dt \end{aligned}$$

Parametar t ide u granicama od x , $[-R, R]$

$$\oint_C \vec{b} \cdot d\vec{e} = \int_{-R}^R (3R^2t^2 - 2t^4) dt + \int_R^{-R} (3R^2t^2 - 2t^4) dt = 0$$

U ovom posebnom slučaju, krumelja je takva da integral ne ovisi ni o putu. U slučaju krumelje u $z=0$ konmu

$$x = R \cos \phi$$

$$y = R \sin \phi$$

$$z = 0$$

\vec{b} nije konzervativno polje!!

Imamo

$$b_x = b_y = 0$$

$$b_z = -R^2 \cos^2 \phi R^2 \sin \phi$$

$$\oint_C \vec{b} \cdot d\vec{e} = \int_0^{2\pi} d\phi R \cdot (R^4 \underbrace{\sin^2 \phi \cos^2 \phi}_{(\frac{1}{2} \sin 2\phi)^2}) = \frac{R^5}{4} \int_0^{2\pi} d\phi \sin^2 2\phi = \frac{R^5}{4} \cdot \frac{1}{2} \cdot 2\pi \neq 0$$

12.1

Parametarske jednačine sfere radijusa R

$$x = R \sin \theta \cos \varphi$$

$$y = R \sin \theta \sin \varphi$$

$$z = R \cos \theta$$

Normala gleda u radialnom smeru. Proverimo!

$$\frac{\partial \vec{r}}{\partial \theta} = (R \cos \theta \cos \varphi, R \cos \theta \sin \varphi, -R \sin \theta)$$

$$\frac{\partial \vec{r}}{\partial \varphi} = (-R \sin \theta \sin \varphi, R \sin \theta \cos \varphi, 0)$$

$$\frac{\partial \vec{r}}{\partial \theta} \times \frac{\partial \vec{r}}{\partial \varphi} = \begin{vmatrix} \vec{e}_x & \vec{e}_y & \vec{e}_z \\ R \cos \theta \cos \varphi & R \cos \theta \sin \varphi & -R \sin \theta \\ -R \sin \theta \sin \varphi & R \sin \theta \cos \varphi & 0 \end{vmatrix} =$$

$$= \vec{e}_x (R^2 \sin^2 \theta \cos \varphi) - \vec{e}_y (-R^2 \sin^2 \theta \sin \varphi) + \vec{e}_z (R^2 \sin \theta \cos \theta \cos^2 \varphi + R^2 \cos \theta \sin \theta \sin^2 \varphi)$$

$$= \vec{e}_x R^2 \sin^2 \theta \cos \theta + \vec{e}_y R^2 \sin^2 \theta \sin \varphi + \vec{e}_z R^2 \sin \theta \cos \theta$$

Ovo se može zapisati u obliku

$$\frac{\partial \vec{r}}{\partial \theta} \times \frac{\partial \vec{r}}{\partial \varphi} = R^2 \sin \theta \vec{e}_r$$

Uvratimo li parametarske jednačine sfere u rektorsko polje

$$\vec{A}(\vec{r}) = R^2 \vec{r}$$

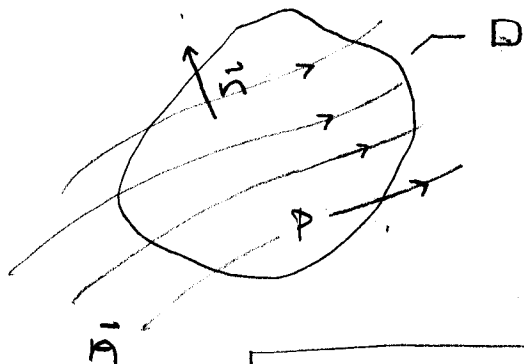
$$\text{gde } \vec{r} = x \vec{e}_x + y \vec{e}_y + z \vec{e}_z.$$

$$\vec{A} \cdot d\vec{S} = \vec{A} \cdot \left(\frac{\partial \vec{r}}{\partial \theta} \times \frac{\partial \vec{r}}{\partial \varphi} \right) d\theta d\varphi = R^2 \vec{r} \cdot R \sin \theta \vec{r} d\theta d\varphi$$

$$= R^3 \sin \theta \underbrace{\vec{r} \cdot \vec{r}}_{r^2 = R^2} d\theta d\varphi = R^5 \sin \theta d\theta d\varphi$$

$$\oint \vec{A} \cdot d\vec{S} = \int_0^{2\pi} d\varphi \int_0^{\pi} d\theta R^5 \sin\theta = \underline{4\pi R^5}$$

Teorem o divergenciji (Gaussov teorem)



D zatvorena ploha koje
omeotuje područje P!

\vec{n} je vanjska normala

$\vec{A} = \vec{A}(\vec{r})$ vektorsko polje

(neprekidno, pravouglone
derivacije neprekidne
 \Rightarrow klas C^1)

$$\boxed{\oint_D \vec{A} \cdot d\vec{S} = \int_P \vec{\nabla} \cdot \vec{A} dV}$$

ZADATAK: treba najprije izračunati $\vec{\nabla} \cdot \vec{A}$

$$\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\frac{\partial A_x}{\partial x} = 3x^2 + y^2 + z^2; \quad \frac{\partial A_y}{\partial y} = x^2 + 3y^2 + z^2; \quad \frac{\partial A_z}{\partial z} = x^2 + y^2 + 3z^2$$

$$\vec{\nabla} \cdot \vec{A} = 5 \underbrace{(x^2 + y^2 + z^2)}_{r^2} = 5r^2$$

$dV = r^2 \sin\theta dr d\theta d\varphi$ u sfernim koordinatama
(zadatak Z3.6)

$$\begin{aligned} \int_V \vec{\nabla} \cdot \vec{A} dV &= \int_0^R \int_0^{2\pi} \int_0^{\pi} 5r^2 \cdot r^2 \sin\theta dr d\theta d\varphi \\ &= 5 \frac{R^5}{5} \cdot 4\pi = \underline{4\pi R^5} \end{aligned}$$